

16-CHEM-B1, TRANSPORT PHENOMENA

DECEMBER 2017

3 hours duration

NOTES

1. If doubt exists as to the interpretation of any question, the candidate is urged to submit with the answer paper, a clear statement of any assumptions made.
2. The examination is an **open book exam**. One textbook of your choice with notations listed on the margins etc., but no loose notes are permitted into the exam.
3. Candidates may use any **non-communicating** calculator.
4. All problems are worth 25 points. **One problem** from **each** of sections A, B, and C must be attempted. A **fourth** problem from **any section** must also be attempted.
5. **Only the first four** questions as they appear in the answer book will be marked.
6. State all assumptions clearly.

SECTION A: Fluid Mechanics

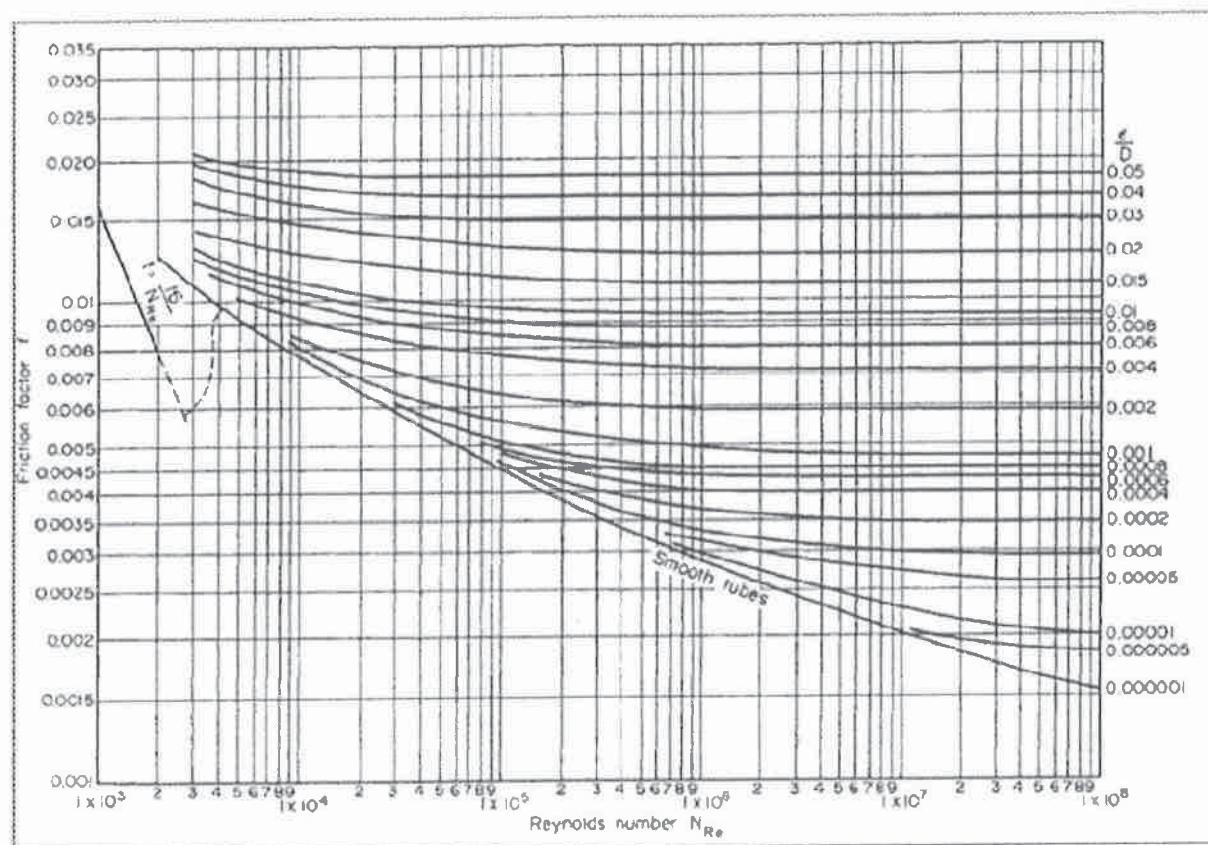
- A1. Three reservoirs of water are located and connected by a piping system. 8.64 liters/second of water is flowing out of the reservoir A through a pipe 61 meters long and 7.8 cm diameter, 4.32 liters/second of water is flowing out of the reservoir B through a pipe 30.5 meters long and 4.32 liters/second of water is flowing out of the reservoir C through a pipe 45.75 meters long. The level of water in reservoir A is 15.25 meters above datum point line, the level of water in reservoir B is 3.05 meters above datum point line and the level of water in reservoir C is 15.25 meters below datum point line. The datum point is the point where pipes from reservoir A, B and C join. Taking the Darcy friction factor of 0.008, calculate the diameters of the pipes from reservoir B and reservoir C.
- A2. Consider a steady, two-dimensional, laminar, constant properties, fully developed flow between two parallel plates separated by a distance “ b ”, flowing with an average velocity U_m . The two dimensions are x (along the direction of the plate) and its perpendicular direction y (along the direction between the plates). If the pressure is independent of y and the body forces are neglected, obtain an expression for the velocity distribution.

SECTION B: Heat Transfer

- B1. Water is flowing through a heat exchanger tube with an inside diameter of 1.25 inches and a length of 9 feet. Water enters at 45 °F with a flow rate of 18 gallons per minute. The tube wall temperature is constant at 200 °F. Assuming the heat exchanger tube to be smooth, determine the exit temperatures of water using analogies of Reynolds, Colburn, Prandtl and von Karmen.

DATA: Prandtl Number of water = 6.78

Kinematic viscosity of water = $1.06 \times 10^{-5} \text{ ft}^2/\text{s}$



Fanning friction factor (f) vs. Reynolds number (Re) for pipes
Transactions of the American Society of Mechanical Engineers, vol. 66, p.672 (1944)

B2. Hot oil flowing at a mass flow rate of \dot{m} passes through a coil of tubes inside a well-stirred tank heats the contents from an entering temperature of T_{in} . Assuming the exit temperature is the same as that inside the tank and if the temperature of the outer surface of the heating coil is T_o ,

- (a) [20 points] Derive an expression for the temperature profile as a function of time.
(b) [5 points] What is expression for temperature for $t = \infty$?

SECTION C: Mass Transfer

C1. A mixture of air and water vapor at 1 atm and 75 °F is passing over a 2 ft long flat plate at a rate of 210 ft/s.

- (a) [20 points] Determine the mass transfer coefficient of water vapor in air if the flow is turbulent and the concentration of water vapor in air is very low, i.e., $P_{bm}/P \approx 1$.
- (b) [5 points] Find the mass transfer coefficient of water vapor in air when the mixture is passing over a sphere of 3 inches diameter instead of a long flat plate. All other conditions remain the same.

DATA: Viscosity of air = 1.24×10^{-5} lb_f/ft.s

Density of air = 7.44×10^{-2} lb/ft³

Diffusivity of water vapor in air = 2.37×10^{-4} ft²/s

C2. Consider the steady-state diffusion of a solute through a membrane sphere (inner radius R_i and outer radius R_o). The region between R_o and R_i defines the membrane, and the solute concentration is highest at the core region. The spheres are placed in a large reservoir and the solute concentration in the bath is zero. Assume that the partition coefficient is one.

- (a) [2 points] State the steady-state form of the differential mass balance for diffusion in a sphere with no convection or reaction.
- (b) [2 points] State the boundary conditions.
- (c) [15 points] Solve to obtain the concentration distribution in the membrane.
- (d) [6 points] Determine the flux at $r = R_o$.

APPENDIX

Summary of the Conservation Equations

Table A.1 The Continuity Equation

	$\frac{\partial \rho}{\partial t} + (\nabla \cdot \rho \vec{u}) = 0$	(1.1)
Rectangular coordinates (x, y, z)	$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho u_x) + \frac{\partial}{\partial y}(\rho u_y) + \frac{\partial}{\partial z}(\rho u_z) = 0$	(1.1a)
Cylindrical coordinates (r, θ, z)	$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r}(\rho r u_r) + \frac{1}{r} \frac{\partial}{\partial \theta}(\rho u_\theta) + \frac{\partial}{\partial z}(\rho u_z) = 0$	(1.1b)
Spherical coordinates (r, θ, ϕ)	$\frac{\partial \rho}{\partial t} + \frac{1}{r^2} \frac{\partial}{\partial r}(\rho r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}(\rho u_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}(\rho u_\phi) = 0$	(1.1c)

Table A.2 The Navier-Stokes equations for Newtonian fluids of constant ρ and μ

	$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = -\frac{1}{\rho} \nabla P + \vec{g} + \nu (\nabla^2 \vec{u})$	(A2)
Rectangular coordinates (x, y, z)		
x -component	$\frac{\partial u_x}{\partial t} + u_x \frac{\partial u_x}{\partial x} + u_y \frac{\partial u_x}{\partial y} + u_z \frac{\partial u_x}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial x} + g_x + \nu \left(\frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_x}{\partial y^2} + \frac{\partial^2 u_x}{\partial z^2} \right)$	(A2a)
y -component	$\frac{\partial u_y}{\partial t} + u_x \frac{\partial u_y}{\partial x} + u_y \frac{\partial u_y}{\partial y} + u_z \frac{\partial u_y}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial y} + g_y + \nu \left(\frac{\partial^2 u_y}{\partial x^2} + \frac{\partial^2 u_y}{\partial y^2} + \frac{\partial^2 u_y}{\partial z^2} \right)$	(A2b)
z -component	$\frac{\partial u_z}{\partial t} + u_x \frac{\partial u_z}{\partial x} + u_y \frac{\partial u_z}{\partial y} + u_z \frac{\partial u_z}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial z} + g_z + \nu \left(\frac{\partial^2 u_z}{\partial x^2} + \frac{\partial^2 u_z}{\partial y^2} + \frac{\partial^2 u_z}{\partial z^2} \right)$	(A2c)

Cylindrical coordinates (r, θ, z)

$$\begin{aligned} r\text{-component} \quad & \frac{\partial u_r}{\partial t} + u_r \frac{\partial u_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_r}{\partial \theta} + u_z \frac{\partial u_r}{\partial z} - \frac{u_\theta^2}{r} \\ & = -\frac{1}{\rho} \frac{\partial P}{\partial r} + g_r + \nu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (ru_r)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial^2 u_r}{\partial z^2} \right] \end{aligned} \quad (\text{A2d})$$

$$\begin{aligned} \theta\text{-component} \quad & \frac{\partial u_\theta}{\partial t} + u_r \frac{\partial u_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + u_z \frac{\partial u_\theta}{\partial z} + \frac{u_r u_\theta}{r} \\ & = -\frac{1}{\rho r} \frac{\partial P}{\partial \theta} + g_\theta + \nu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial (ru_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} + \frac{\partial^2 u_\theta}{\partial z^2} \right] \end{aligned} \quad (\text{A2e})$$

$$\begin{aligned} z\text{-component} \quad & \frac{\partial u_z}{\partial t} + u_r \frac{\partial u_z}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_z}{\partial \theta} + u_z \frac{\partial u_z}{\partial z} \\ & = -\frac{1}{\rho} \frac{\partial P}{\partial z} + g_z + \nu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_z}{\partial \theta^2} + \frac{\partial^2 u_z}{\partial z^2} \right] \end{aligned} \quad (\text{A2f})$$

Spherical coordinates (r, θ, ϕ)

$$\begin{aligned} r\text{-component} \quad & \frac{\partial u_r}{\partial t} + u_r \frac{\partial u_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_r}{\partial \theta} + \left(\frac{u_\phi}{r \sin \theta} \right) \frac{\partial u_r}{\partial \phi} - \frac{u_\theta^2}{r} - \frac{u_\phi^2}{r} = -\frac{1}{\rho} \frac{\partial P}{\partial r} + g_r \\ & + \nu \left[\frac{1}{r^2} \frac{\partial^2}{\partial r^2} (r^2 u_r) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial u_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_r}{\partial \phi^2} \right] \end{aligned} \quad (\text{A2g})$$

$$\begin{aligned} \theta\text{-component} \quad & \frac{\partial u_\theta}{\partial t} + u_r \frac{\partial u_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + \left(\frac{u_\phi}{r \sin \theta} \right) \frac{\partial u_\theta}{\partial \phi} + \frac{u_r u_\theta}{r} - \frac{u_\phi^2}{r} \cot \theta = -\frac{1}{\rho r} \frac{\partial P}{\partial \theta} + g_\theta \\ & + \nu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial u_\theta}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (u_\theta \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\theta}{\partial \phi^2} \right. \\ & \left. + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial u_\phi}{\partial \phi} \right] \end{aligned} \quad (\text{A2h})$$

$$\begin{aligned} \phi\text{-component} \quad & \frac{\partial u_\phi}{\partial t} + u_r \frac{\partial u_\phi}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{u_r u_\phi}{r} + \frac{u_\theta u_\phi}{r} \cot \theta = -\frac{1}{\rho r \sin \theta} \frac{\partial P}{\partial \phi} \\ & + g_\phi + \nu \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial u_\phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (u_\phi \sin \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u_\phi}{\partial \phi^2} \right. \\ & \left. + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \phi} + \frac{2 \cot \theta}{r^2 \sin \theta} \frac{\partial u_\theta}{\partial \phi} \right] \end{aligned} \quad (\text{A2i})$$

Table A.3 The Energy Equation for Incompressible Media

$\rho c_p \left[\frac{\partial T}{\partial t} + (\vec{u} \cdot \nabla)(T) \right] = [\nabla \cdot k \nabla T] + \dot{T}_G \quad (A3)$
Rectangular coordinates (x, y, z)
$\rho c_p \left[\frac{\partial T}{\partial t} + u_x \frac{\partial T}{\partial x} + u_y \frac{\partial T}{\partial y} + u_z \frac{\partial T}{\partial z} \right] = \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \dot{T}_G \quad (A3a)$
Cylindrical coordinates (r, θ, z)
$\rho c_p \left[\frac{\partial T}{\partial t} + u_r \frac{\partial T}{\partial r} + \frac{u_\theta}{r} \frac{\partial T}{\partial \theta} + u_z \frac{\partial T}{\partial z} \right] = \frac{1}{r} \frac{\partial}{\partial r} \left(rk \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(k \frac{\partial T}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) + \dot{T}_G \quad (A3b)$
Spherical coordinates (r, θ, ϕ)
$\rho c_p \left[\frac{\partial T}{\partial t} + u_r \frac{\partial T}{\partial r} + \frac{u_\theta}{r} \frac{\partial T}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial T}{\partial \phi} \right] =$ $\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 k \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(k \sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \phi} \left(k \frac{\partial T}{\partial \phi} \right) + \dot{T}_G \quad (A3c)$

Table A4: The continuity equation for species A in terms of the molar flux

$\frac{\partial C_A}{\partial t} = -(\nabla \cdot \vec{N}_A) + \dot{R}_{A,G} \quad (4.)$
Rectangular coordinates (x, y, z)
$\frac{\partial C_A}{\partial t} = -\left(\frac{\partial [N_A]_x}{\partial x} + \frac{\partial [N_A]_y}{\partial y} + \frac{\partial [N_A]_z}{\partial z} \right) + \dot{R}_{A,G} \quad (4a)$
Cylindrical coordinates (r, θ, z)
$\frac{\partial C_A}{\partial t} = -\left\{ \frac{1}{r} \frac{\partial}{\partial r} [r N_A]_r + \frac{1}{r} \frac{\partial}{\partial \theta} [N_A]_\theta + \frac{\partial}{\partial z} [N_A]_z \right\} + \dot{R}_{A,G} \quad (4b)$
Spherical coordinates (r, θ, ϕ)
$\frac{\partial C_A}{\partial t} = -\left\{ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 [N_A]_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} ([N_A]_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} [N_A]_\phi \right\} + \dot{R}_{A,G} \quad (4c)$

Table A.5: The continuity equation for species A

$$\frac{\partial C_A}{\partial t} + (\vec{u} \cdot \nabla) C_A = D_A \nabla^2 C_A + \dot{R}_{A,G} \quad (5)$$

Rectangular coordinates (x, y, z)

$$\frac{\partial C_A}{\partial t} + u_x \frac{\partial C_A}{\partial x} + u_y \frac{\partial C_A}{\partial y} + u_z \frac{\partial C_A}{\partial z} = \frac{\partial}{\partial x} \left(D \frac{\partial C_A}{\partial x} \right) + \frac{\partial}{\partial y} \left(D \frac{\partial C_A}{\partial y} \right) + \frac{\partial}{\partial z} \left(D \frac{\partial C_A}{\partial z} \right) + \dot{R}_{A,G} \quad (5a)$$

Cylindrical coordinates (r, θ, z)

$$\frac{\partial C_A}{\partial t} + u_r \frac{\partial C_A}{\partial r} + \frac{u_\theta}{r} \frac{\partial C_A}{\partial \theta} + u_z \frac{\partial C_A}{\partial z} = \frac{1}{r} \frac{\partial}{\partial r} \left(r D \frac{\partial C_A}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(D \frac{\partial C_A}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(D \frac{\partial C_A}{\partial z} \right) + \dot{R}_{A,G} \quad (5b)$$

Spherical coordinates (r, θ, ϕ)

$$\begin{aligned} \frac{\partial C_A}{\partial t} + u_r \frac{\partial C_A}{\partial r} + \frac{u_\theta}{r} \frac{\partial C_A}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial C_A}{\partial \phi} &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 D \frac{\partial C_A}{\partial r} \right) \\ &+ \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(D \sin \theta \frac{\partial C_A}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \phi} \left(D \frac{\partial C_A}{\partial \phi} \right) + \dot{R}_{A,G} \end{aligned} \quad (5c)$$

